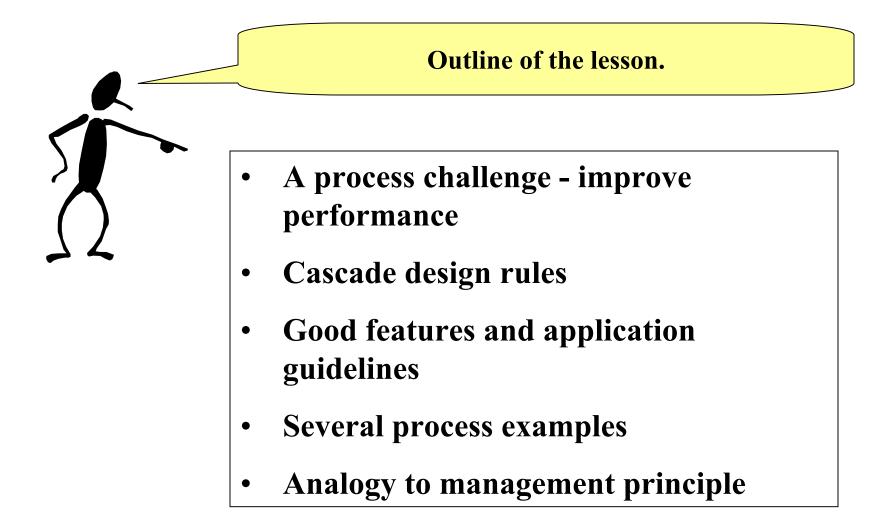
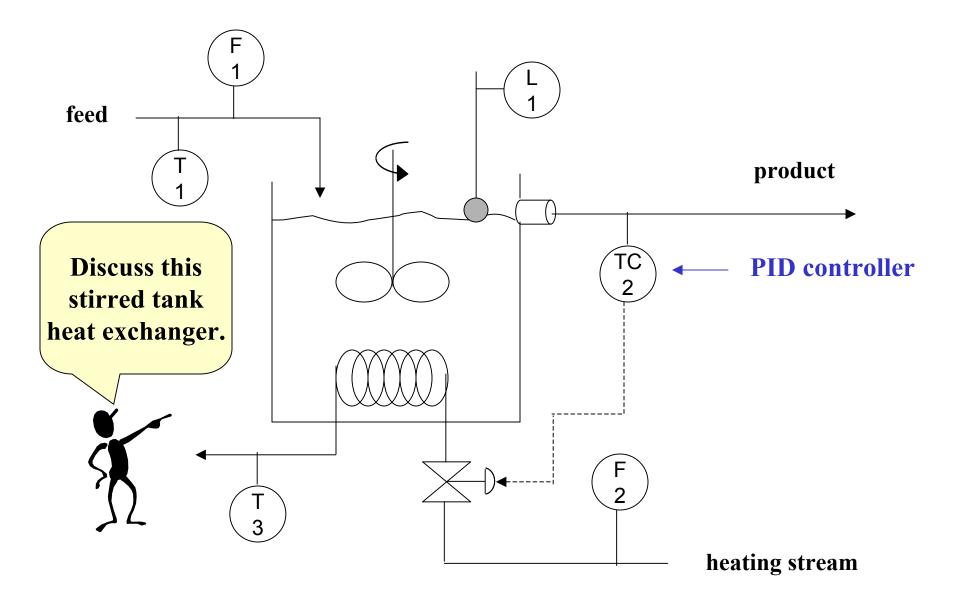
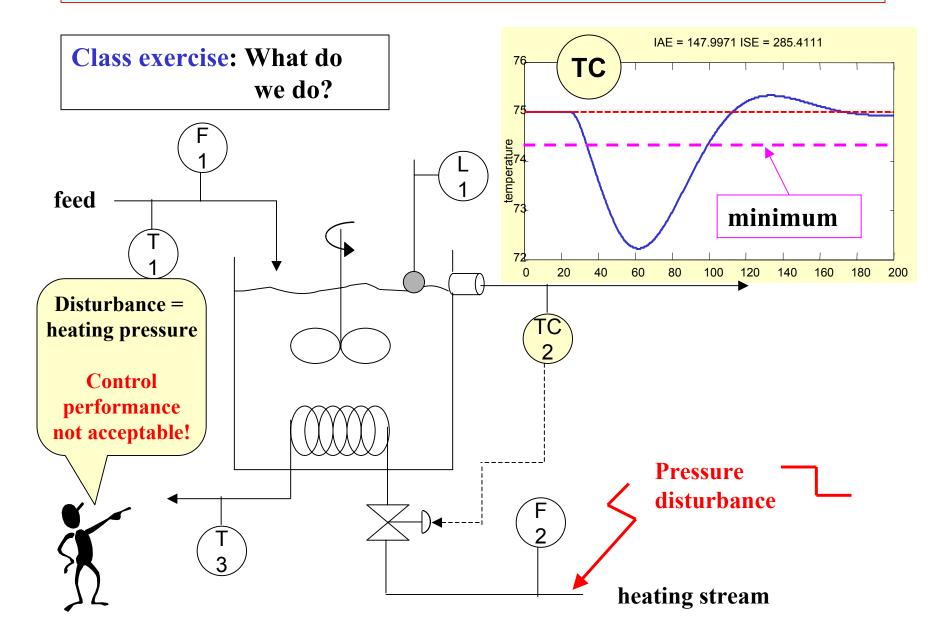
When I complete this chapter, I want to be able to do the following.

- Identify situations for which cascade is a good control enhancement
- Design cascade control using the five design rules
- Apply the tuning procedure to cascade control

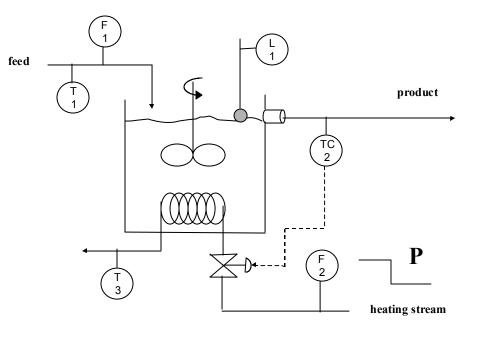






Let's think about the process behavior.

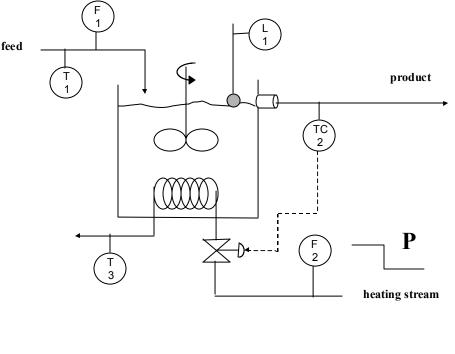
- Causal relationship from P disturbance to T (without control)
- What measurable effect always occurs when P changes?



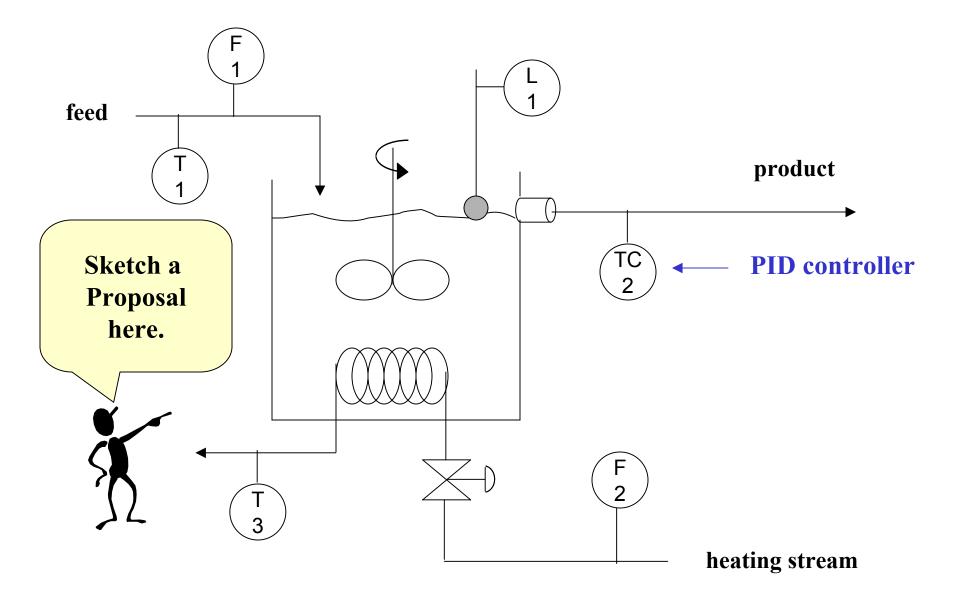
$$\begin{array}{cccc} v \ (valve) \rightarrow & \ref{eq: red} & \ref{eq: re$$

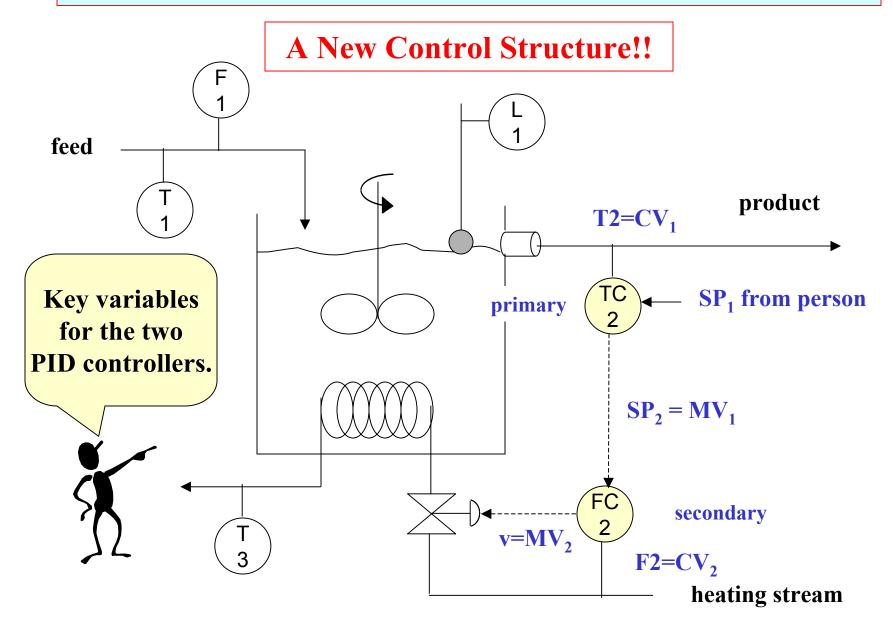
#### <u>Let's think about the</u> <u>process behavior.</u>

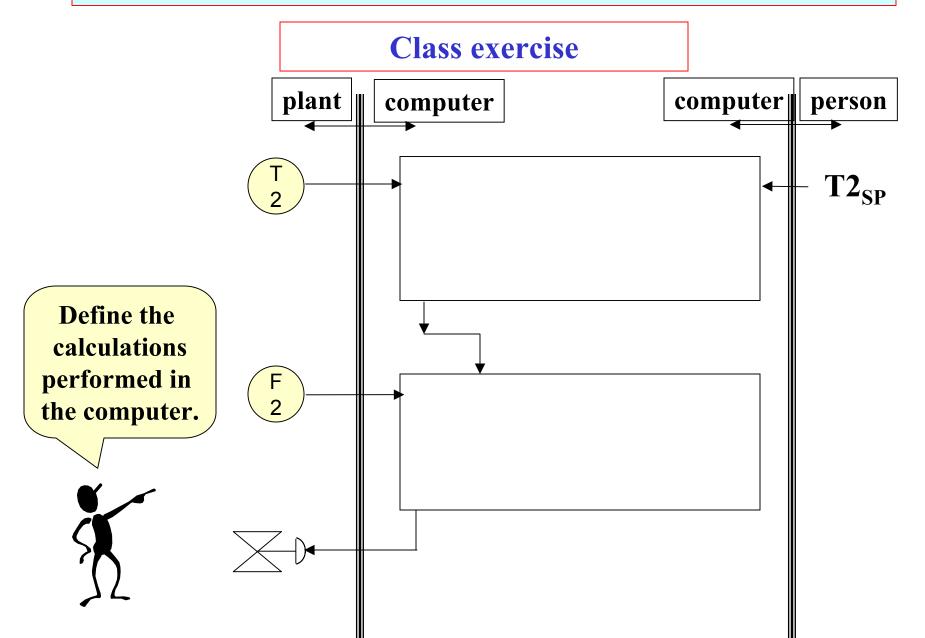
If we can maintain this variable approximately constant, can we reduce the effect of the disturbance?

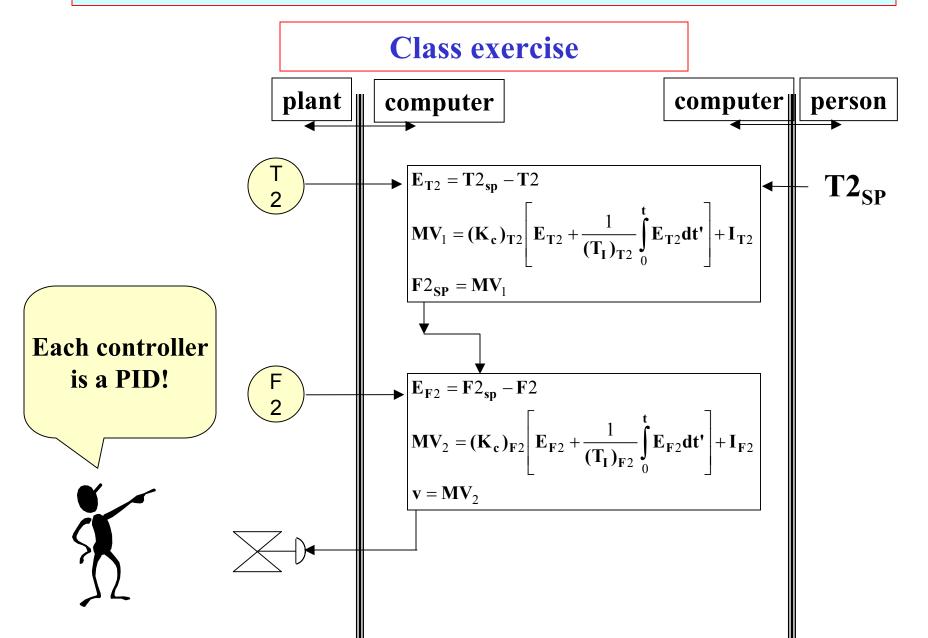


$$v \text{ (valve)} \rightarrow (???) \rightarrow Q \rightarrow TC$$
  
 $P$   
(heating oil)





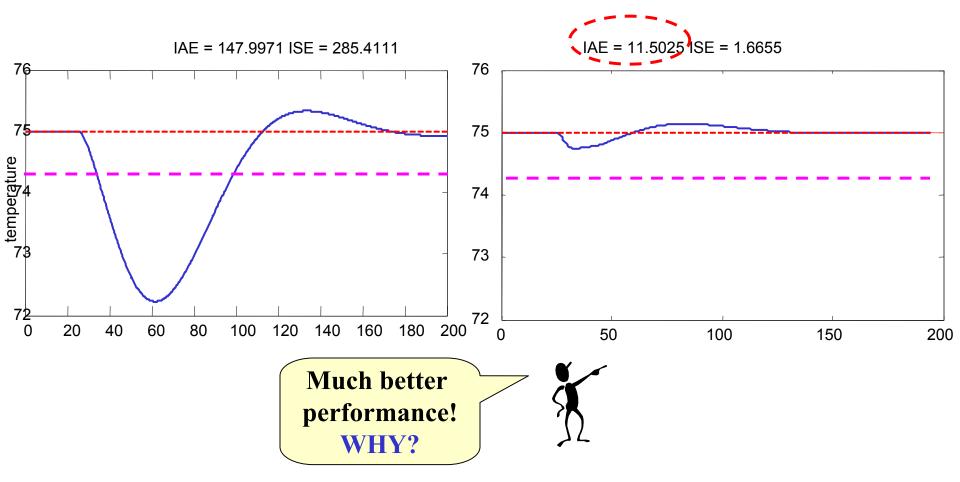




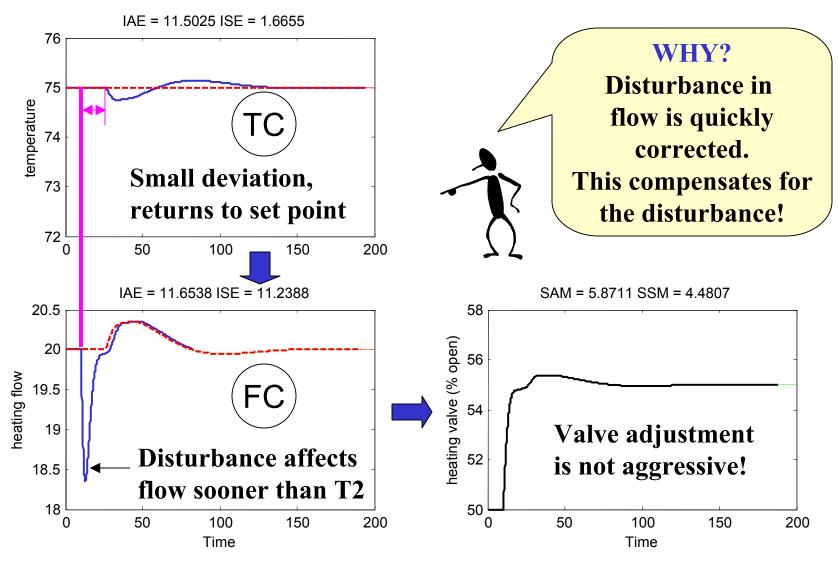
# **Control Performance Comparison for CST Heater**

#### Single-Loop

#### Cascade

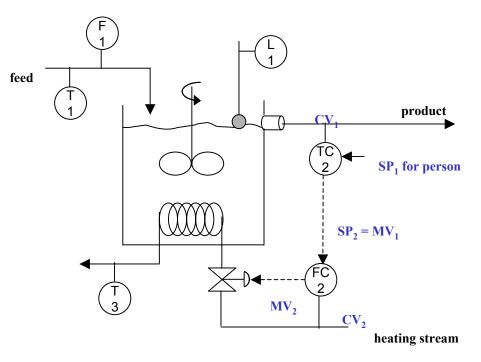


#### **Cascade Control Performance for CST Heater**



What have we gained and lost using cascade control?

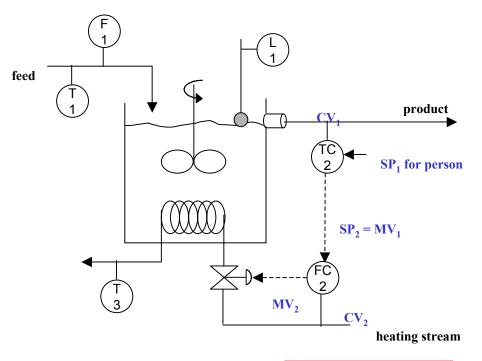
For each case, is cascade better, same, worse than single-loop feedback (TC2  $\rightarrow$  v)?



- A disturbance in heating medium inlet pressure
- A disturbance in heating medium inlet temperature
- A disturbance in feed flow rate
- A change to the TC set point

What have we gained and lost using cascade control?

For each case, is cascade better, same, worse than single-loop feedback (TC2  $\rightarrow$  v)?



- A disturbance in heating medium inlet pressu Cascade better
- A disturbance in heating medium inlet tempe Both the same
- A disturbance in feed flow rate
- A change to the TC set point



#### **CASCADE DESIGN CRITERIA**

- Cascade is desired when
- 1. Single-loop performance unacceptable
- 2. A measured variable is available

#### <u>A secondary variable must</u>

- 3. Indicate the occurrence of an important disturbance
- 4. Have a causal relationship from valve to secondary (cause  $\rightarrow$  effect)
- 5. Have a faster response than the primary

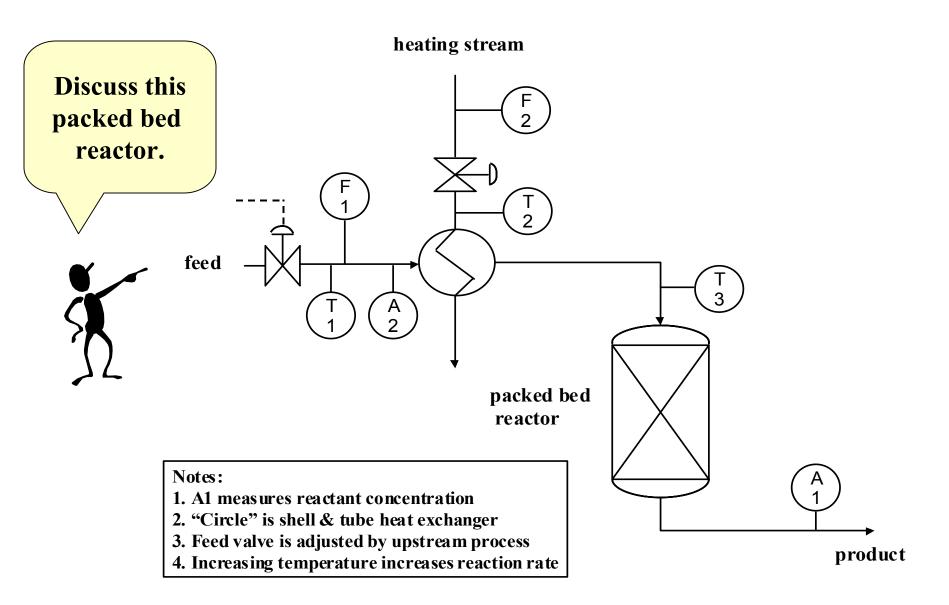


#### **ADVANTAGES OF CASCADE CONTROL**

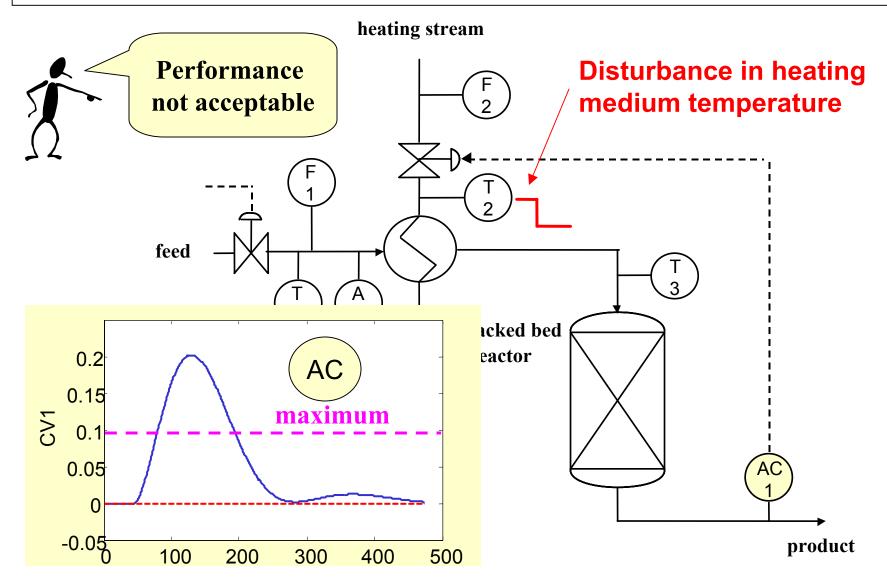
- Large improvement in performance when the secondary is much faster than primary
- Simple technology with PID algorithms
- Use of feedback at all levels. Primary has zero offset for "step-like" disturbances.
- Plant operating personnel find cascades easy to operate. Open a cascade at one level, and all controllers <u>above are inactive</u>.

#### **CLASS EXERCISE: SOME QUESTIONS ABOUT** CASCADE CONTROL

- Why do we retain the primary controller?
- Which modes are required for zero steady-state offset?
- Which modes are recommended?
- What is the additional cost for cascade control?
- Normally, each PID controller represents one independent controlled variable. Is anything different in a cascade structure?
- What procedure is used for tuning cascade control?

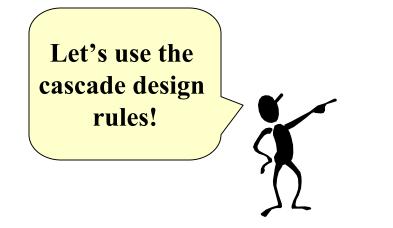


**Class exercise:** Design a cascade control structure to improve performance.



**Class exercise:** Design a cascade control structure to improve performance.

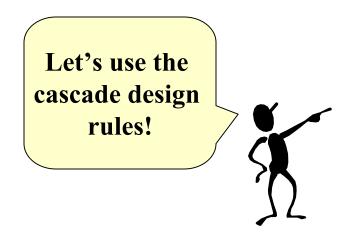
Cascade design criteria	A2	<b>F1</b>	<b>F2</b>	<b>T1</b>	<b>T2</b>	<b>T3</b>
1. Single-loop not acceptable						
2. Secondary variable is measured						
3. Indicates a key disturbance						
4. Causal relationship, valve $\rightarrow$ secondary						
5. Secondary dynamics faster than primary						



**Remember:** The disturbance is the heating medium inlet temperature and the primary is AC-1.

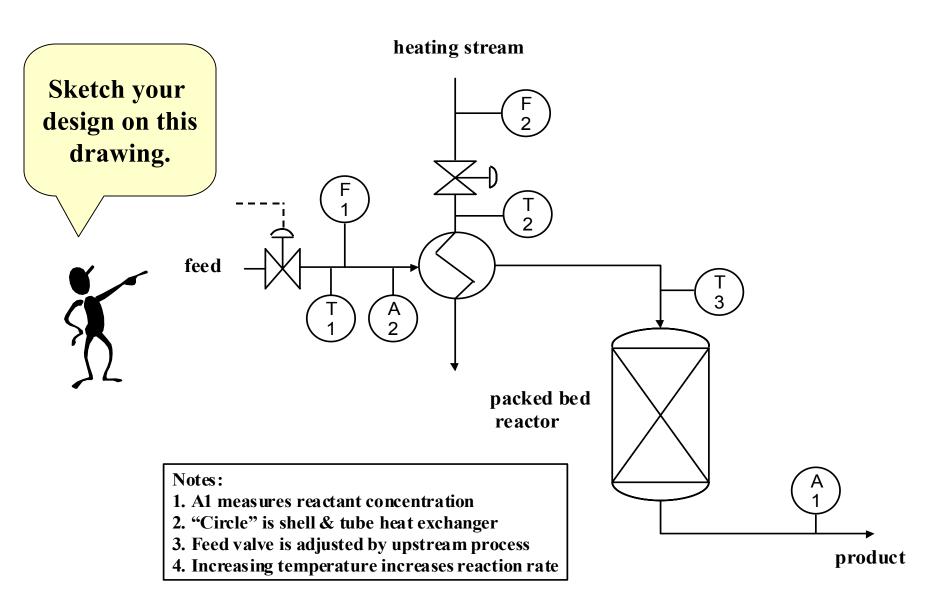
**Class exercise:** Design a cascade control structure to improve performance.

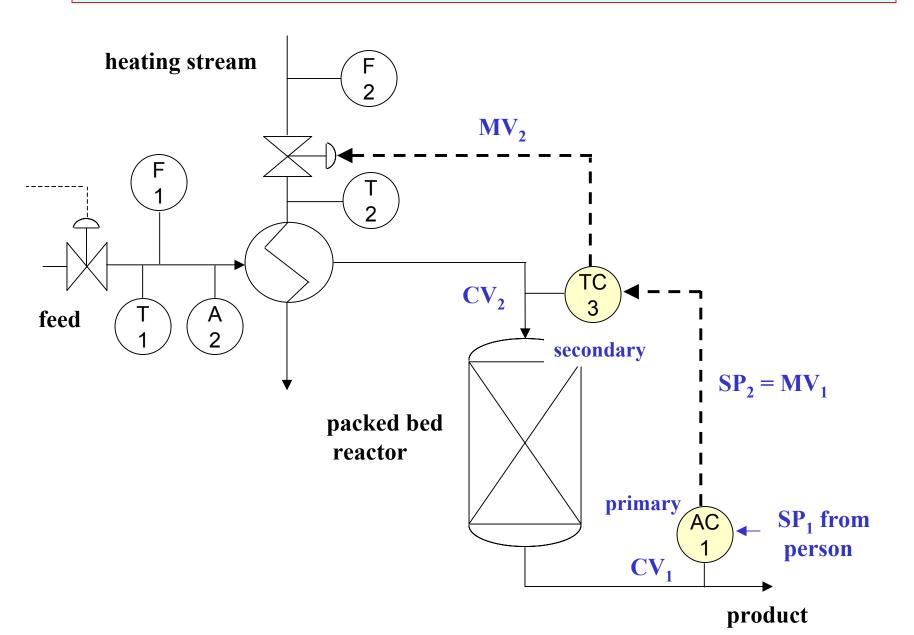
Cascade design criteria	A2	<b>F1</b>	<b>F2</b>	<b>T1</b>	T2	<b>T3</b>
1. Single-loop not acceptable	Y	Y	Y	Y	Y	Y
2. Secondary variable is measured	Y	Y	Y	Y	Y	Y
3. Indicates a key disturbance	Ν	Ν	Ν	Ν	Y	Y
4. Causal relationship, valve $\rightarrow$ secondary	N	Ν	Y	Ν	Ν	Y
5. Secondary dynamics faster than primary	N/A	N/A	N/A	N/A	N/A	Y



T2 is the disturbance but cannot be used in cascade!

> T3 satisfies all of the rules and can be used as a secondary in a cascade.

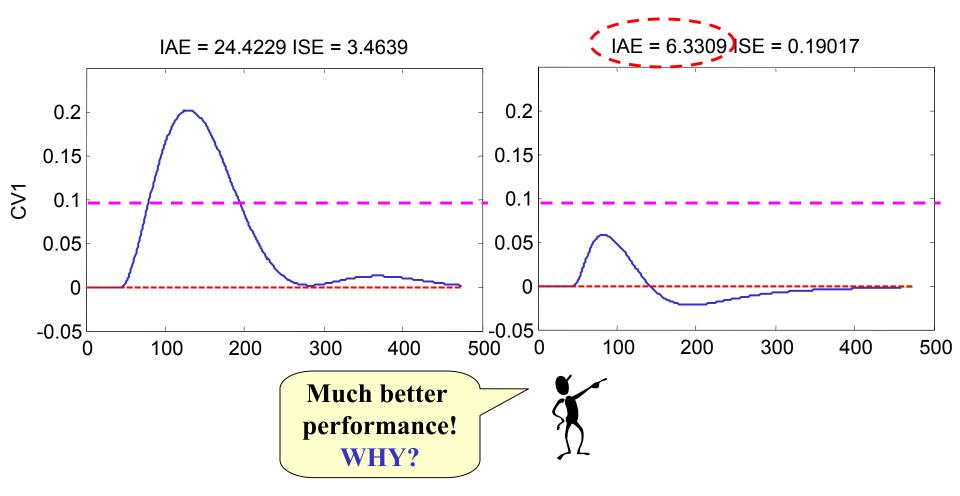


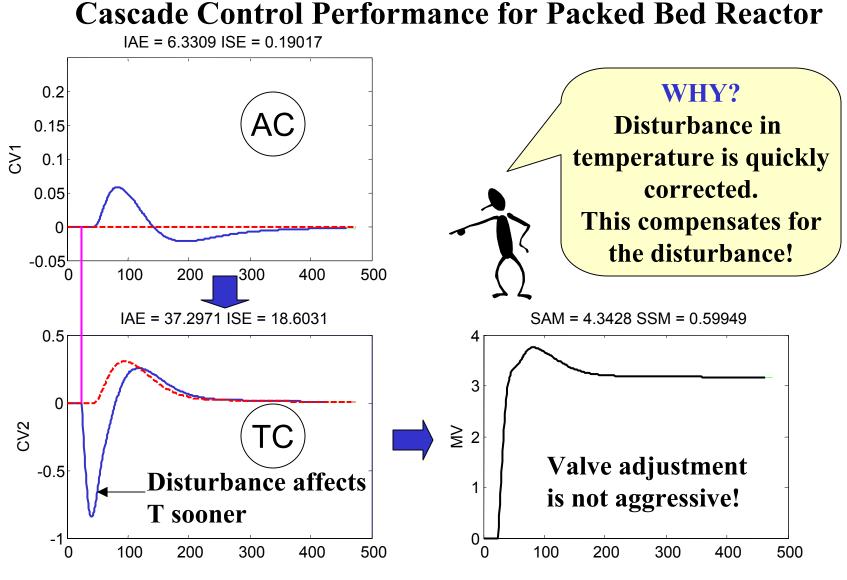


#### **Control Performance Comparison for Packed Bed Reactor**

Single-Loop

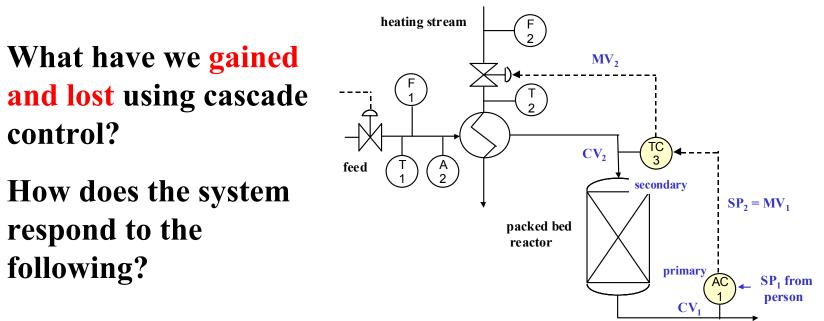
Cascade





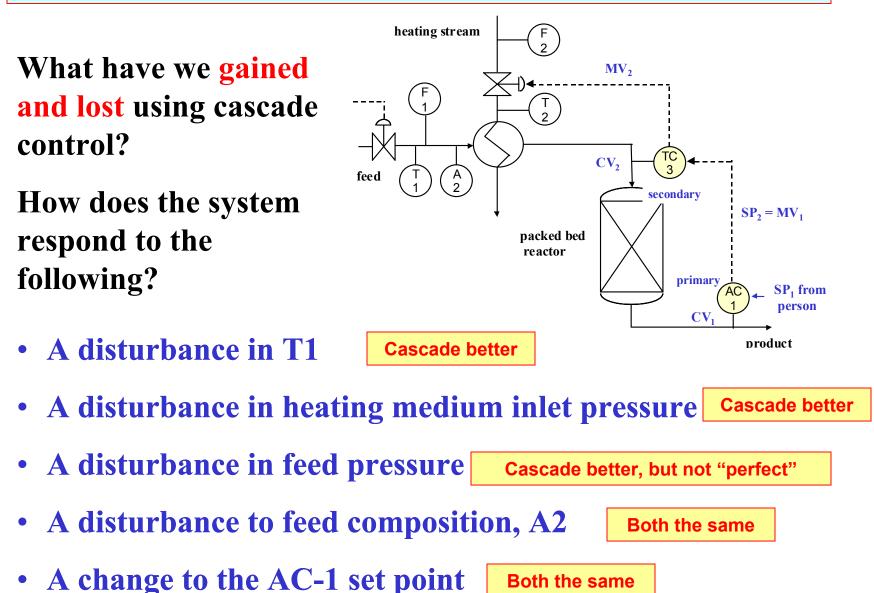
Time

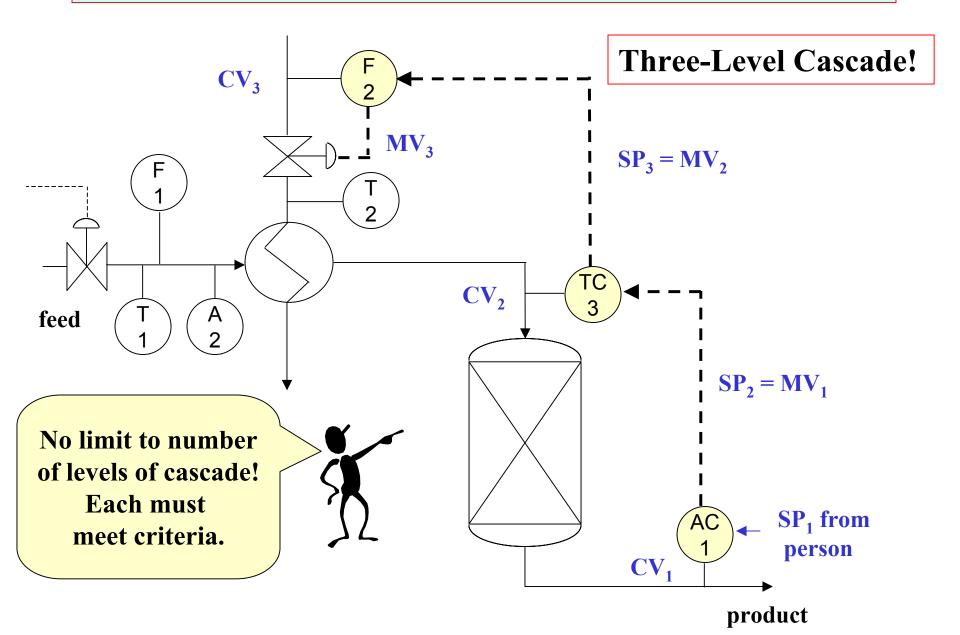
Time

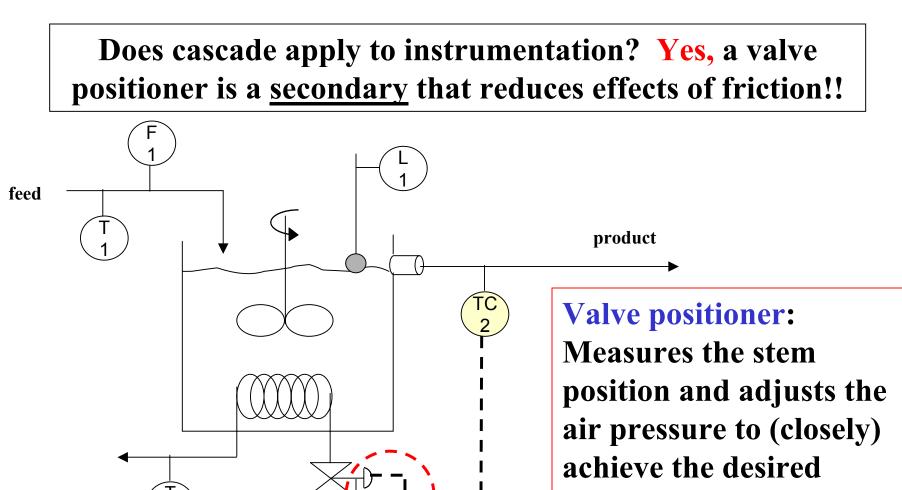


product

- A disturbance in T1
- A disturbance in heating medium inlet pressure
- A disturbance in feed pressure
- A disturbance to feed composition, A2
- A change to the AC-1 set point







position. This is located

at the valve.

heating stream



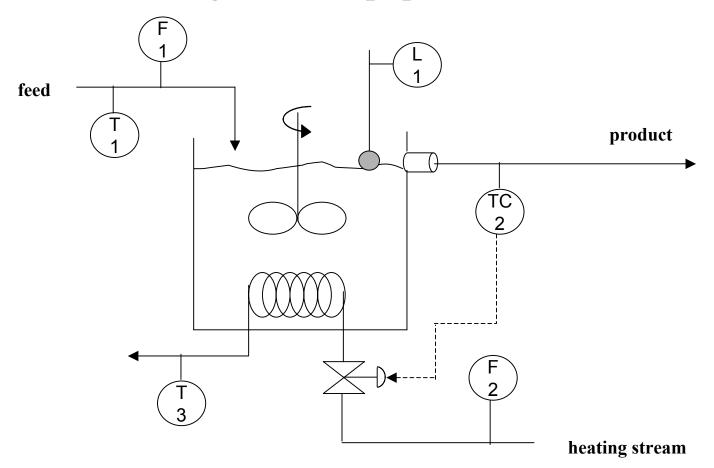
A cascade is a hierarchy, with decisions transmitted from upper to lower levels.

No communication flows up the hierarchy.

- What are advantages of a hierarchy?
- What information should be transmitted up the hierarchy?
- What information should flow from secondary to primary in a cascade?

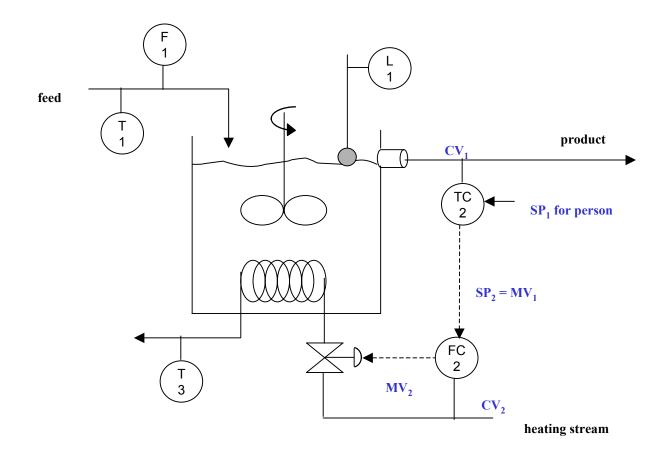
#### **CHAPTER 14: CASCADE CONTROL WORKSHOP 1**

Evaluate cascade control for a disturbance in the heating medium inlet temperature. You may add a sensor but make no other changes to the equipment.



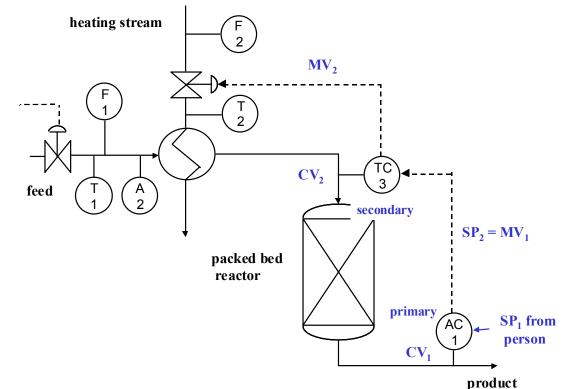
#### **CHAPTER 14: CASCADE CONTROL WORKSHOP 2**

# Prepare a detailed plan for tuning the two cascade controllers shown in the following sketch.



#### **CHAPTER 14: CASCADE CONTROL WORKSHOP 3**

Prepare a flowchart for the calculations performed by the packed bed cascade controllers. Show every calculation and use process variable symbols (e.g., A1), not generic symbols ( $CV_1$ ).



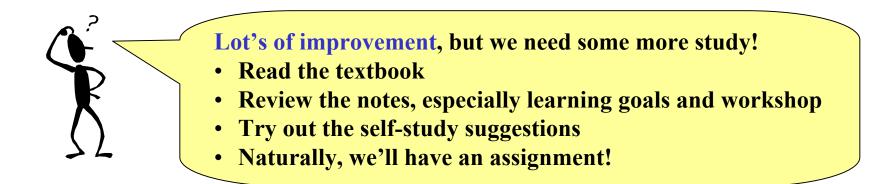
#### Identify process examples in which a valve positioner will improve performance and not improve performance.

# Draw a sketch of each process and discuss your recommendation of whether or not to use a positioner.

**Note:** Modern positioners provide diagnosis of the valve behavior that can be transmitted digitally for later evaluation. This can be very useful in maintenance and trouble shooting.

When I complete this chapter, I want to be able to do the following.

- Identify situations for which cascade is a good control enhancement
- Design cascade control using the five design rules
- Apply the tuning procedure to cascade control



## **CHAPTER 14: LEARNING RESOURCES**

#### • **SITE PC-EDUCATION WEB**

- Instrumentation Notes
- Interactive Learning Module (Chapter 14)
- Tutorials (Chapter 14)
- S\_LOOP
  - Dynamic simulation of linear system
- The Textbook, naturally, for many more examples

#### **CHAPTER 14: SUGGESTIONS FOR SELF-STUDY**

1. Prove that an integral mode is required for zero steadystate offset of the primary.

Do we achieve zero offset for the secondary. Why or why not?

Is there any advantage for achieving zero offset for the secondary?

- 2. Program a cascade control for one of the processes modelled in Chapters 3-5.
- **3.** Determine a guideline for how much faster the secondary must be than the primary for cascade to function well.

#### **CHAPTER 14: SUGGESTIONS FOR SELF-STUDY**

- 4. Using block diagram algebra, derive the transfer functions in textbook equations (14.6) to (14.8).
- 5. Review the following publication to find other advantages for cascade control.

Verhaegen, S., When to use cascade control, *Intech*, 38-40 (Oct. 1991).

6. Discuss applications of cascade control (hierarchical decision systems) in business, government, and university. Explain advantages and disadvantages of these systems.